

# CURRICULUM VITAE

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Dr. ir. Johannes T. B. Overvelde

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Website: [www.overvelde.com](http://www.overvelde.com)  
[www.amolf.nl/research-groups/soft-robotic-matter](http://www.amolf.nl/research-groups/soft-robotic-matter)  
[www.studioovervelde.com](http://www.studioovervelde.com)  
[www.linkedin.com/in/overvelde](http://www.linkedin.com/in/overvelde)  
[www.researchgate.net/profile/johannes\\_overvelde](http://www.researchgate.net/profile/johannes_overvelde)



## WORK EXPERIENCE

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- 2016-present: Soft Robotic Matter Group, AMOLF (NL)  
**Principal Investigator**  
Current group members: Niels Commandeur (Technician), Udit Choudhury (Postdoc), Giorgio Oliveri, Agustin Iniguez Rabago, Luuk van Laake, Maziar Arfaee (PhD-student), Clara Miette, Anastassia Milleret, Anne Pasman, Simon van Hurne, Cesare Carissimo (Interns)  
Past group members: Dario Mula Albert, Sukanth Karapakula, Yun Li Intern, Mark ten Hooven Intern, Andor Bent Intern, Sami Laroui Intern, Rick Jongerius, Leah Dickhoff Intern, Charlie Maslen, Fatemeh Kazem Zadeh, Yannick Blommert, Davide Bray (Interns), Aravind Jayasankar (Guest)
- 2017-present: Studio Overvelde (NL)  
**Technical Consultant**
- 2011-2012: Femto Engineering (NL)  
**Consultant**, R&D and FEM engineer
- 2009-2010: Department of Industrial Design, TU Delft (NL)  
**Warehouse and Personnel Manager**

## EDUCATION

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- 2012-2016: School of Engineering and Applied Sciences, Harvard University (US)  
**PhD** in Applied Mathematics  
PhD dissertation: 'Embracing Compliance and Instabilities to Achieve Function in Mechanical Meta-materials and Devices'. Advisor prof. Katia Bertoldi.
- 2012-2013: School of Engineering and Applied Sciences, Harvard University (US)  
**SM** in Applied Mathematics
- 2009-2012: TU Delft (NL)  
**MSc** in Mechanical Engineering  
*Cum laude* (GPA 4.0 - 8,7/10).  
Specialization: Solid and Fluid Mechanics.  
Master's thesis: 'The Moving Node Approach in Topology Optimization - An Exploration to a Flow-inspired Meshless Method-based Topology Optimization Method'. Advisors prof. dr. ir. Fred van Keulen and dr. ir. Matthijs Langelaar. [\[pdf\]](#)  
Research Internship: 'The Effect of Shape on Periodic Structures Undergoing Elastic Instability', Harvard University (US).
- 2006-2009: TU Delft (NL)  
**BSc** in Mechanical Engineering  
*Cum laude* (GPA 3.9 - 7,9/10).  
Bachelor's thesis: 'Cavitation-treatment Times of a Liquid'. [\[pdf\]](#)
- 2004-2009: TU Delft (NL)  
**P** (propaedeutic exam) in Applied Physics
- 1998-2004: CSG het Noordik, Almelo (NL)  
**VWO** (preparatory scientific education)

## TEACHING

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- Spring 2014: School of Engineering and Applied Sciences, Harvard University (US)  
**Teaching Fellow** ES128 Computational Solid and Structural Mechanics

- 2008-2009: Department of Industrial Design, TU Delft (NL)  
**Lab Instructor** WBTP113-07 and WBTP115 drilling, milling, turning and welding
- 2008-2009: Cultural Center Delft (NL)  
**Instructor** weekly juggling workshops

## SCHOLARSHIPS & AWARDS

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- 2017: Veni Innovational Research Incentives Scheme, NWO  
2017: H2020-FETOPEN, European Commission  
2017: European cooperation project “Les Voyages de Capitaine futur”  
2017: KIEM Creative Industry, NWO  
2017: Postdoc competition, AMOLF  
2015: 1st prize winner of the Gallery of Mechanics at New.Mech 2015, Boston University  
2014: Certificate of Excellence and Distinction in Teaching for the course ES128, Derek Bok Center for Teaching and Learning, Harvard University  
2014: Haythornthwaite Foundation Student Travel Award, ASME AMD  
2014: Robert L. Wallace Prize Fellowship, Harvard University  
2013: Robert L. Wallace Prize Fellowship, Harvard University  
2012: UfD-Best Graduate of 3mE Faculty Grant, TU Delft  
2012: Fulbright Grant, The Fulbright Center  
2012: University Fund Delft Grant, TU Delft  
2011: Employee of the Year Award, Femto Engineering  
2010: Justus & Louise van Effen Excellence Scholarship, TU Delft  
2009: Best Research Award, BSc thesis TU Delft

## PROFESSIONAL SERVICE

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### Ad hoc reviewer

Science, Science Advances, Nature, Nature Materials, Nature Physics, Nature Communications, Nature Energy, PNAS, Soft Robotics, Soft Matter, PRL, PRX, EML, IEEE/ASME International Conference on Advanced Intelligent Mechatronics, SIAM Journal on Scientific Computing

### Professional membership

The American Society of Mechanical Engineers (ASME)  
American Physical Society (APS)  
Society of Engineering Science (SES)

### Session organizer and chair

Co-organizer of sessions at the APS March Meeting (2017-2020) and at SES (2018-2019)

### Review grant proposals and scholarships

JKU LIT, TTW OTP, DFG Priority Programme “Soft Robotic Material Systems” (SPP 2100), ENIAC scholarship

### MSME Committee member (2014-2016), Harvard University (US)

Social and year-end event committee from the Materials Science and Mechanical Engineering department

### Organizer open day (2016-2019), AMOLF (NL)

## INVITED TALKS & COLLOQUIA

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- 2019 Hyber, Helsinki FI  
**Invited talk:** Soft Robotic Matter
- 2019 ICMS Outreach Symposium, Eindhoven NL  
**Invited talk:** Sequential Actuation of Soft Robots by Harnessing Soft Fluidic Networks
- 2019 Studium Generale, Groningen NL  
**Keynote talk:** Origami-inspired Materials and Robots
- 2018 ASME IMECE, Pittsburgh US  
**Invited talk:** Computational Design of Multistable Prismatic Architected Materials
- 2018 Fablearn, Eindhoven NL  
**Masterclass:** RainMaker: from Mechanical Metamaterial to Interactive Art Installation
- 2018 The Hamlyn Symposium on Medical Robotics, London UK

- Invited talk:** Programming the Response of Fluidic Soft Actuators by Harnessing Nonlinearities
- 2018 ReMAR, Delft NL  
**Invited talk:** Transforming Materials
- 2018 Equinix, Amsterdam NL  
**Keynote talk:** Mathemagical interconnections
- 2018 Nationale Wiskundedagen, Noordwijkerhout (NL)  
**Invited talk:** Van Origami-materialen naar Zachte Robots
- 2018 Physics@Veldhoven, Veldhoven (NL)  
**Invited talk:** Rational Design of Reconfigurable Architected Materials
- 2018 Gordon Conference Multifunctional Materials and Structures, Ventura (US)  
**Invited talk:** Finding the Mechanically Stable States in Prismatic Architected Materials
- 2017 SURFnet, Utrecht (NL)  
**Invited talk:** Van Origami-materialen naar Zachte Robots
- 2017 Ars and Mathesis, Utrecht (NL)  
**Invited talk:** Transforming Materials
- 2017 ARCNL, Amsterdam (NL)  
**Invited talk:** Embracing compliance and instabilities in mechanical systems
- 2017 TEDxGroningen, Groningen (NL)  
**Invited talk:** What can we learn from crumpling a piece of paper?
- 2017 School of Architecture, TU Delft (NL)  
**Invited talk:** Guest Lecturer in Robotic Building - Media Studies
- 2017 AMOLF Open Dag, Amsterdam (NL)  
**Invited talk:** Van Origami-materialen naar Zachte Robots
- 2017 HMC Zomeracademie, Rotterdam (NL)  
**Invited talk:** Magic Materials make Soft Robots
- 2017 Soft and Biological Matter Seminar, Leiden (NL)  
**Invited talk:** Rational Design of Reconfigurable Architected Materials
- 2017 PINC.18 Conference, Utrecht (NL)  
**Invited talk:** Magic Materials make Soft Robots
- 2017 SMS Europe, Paris (FR)  
**Invited talk:** Rational Design of Reconfigurable Architected Materials
- 2017 AMOLF, Amsterdam (NL)  
**public colloquium:** Rational Design of Reconfigurable Devices and Architected Materials
- 2016: AMOLF, Amsterdam (NL)  
**Friday seminar:** Soft Robotic Matter
- 2016: 3D Printing Materials Conference, Maastricht (NL)  
**Invited talk:** Embracing Compliance in Robots to Achieve Function
- 2015: Designer Matter, AMOLF (NL)  
**Invited talk:** Controlling Soft Structures and Devices by Embedded Actuation and Sensing
- 2015: Aerospace Structures and Computational Mechanics, TU Delft (NL)  
**Invited talk:** Actuated Materials, Smart Actuated Structures and Devices that Harness Compliance and Instabilities
- 2015: Institute Lorentz, Leiden University (NL)  
**Soft Matter Physics Seminar:** Mechanical Metamaterials that Harness Instabilities and Folding
- 2015: School of Engineering and Applied Sciences, Harvard University (US)  
**MSME Year End Event:** From Origami to Transformable Metamaterials
- 2015: Graduate School of Design, Harvard University (US)  
**Guest Lecturer** in Computational Material Distributions and Gradients of Compliance (SCI 0642500)
- 2014: Wyss Institute for Biologically Inspired Engineering, Harvard University (US)  
**Soft Robotics General Meeting:** Finite Element Analysis of Soft Liquid Embedded Strain Sensors

- 2014: School of Engineering and Applied Sciences, Harvard University (US)  
**Mech & Math:** Instabilities in Pressure-Volume relation of inflatable Membranes
- 2014: Graduate School of Design, Harvard University (US)  
**Guest Lecturer** in Computational Material Distributions and Gradients of Compliance (SCI 0642500)
- 2012: School of Engineering and Applied Sciences, Harvard University (US)  
**Mech & Math:** Shape Optimization of Soft Periodic Structures
- 2010: School of Engineering and Applied Sciences, Harvard University (US)  
**Abaqus Masterclass**

## CONFERENCES

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- (28) **van Laake, L., Overvelde, J. T. B.**, (2019). Mechanically Programmable Sequential Actuation of Fluid-driven Soft Actuators. APS March Meeting. Boston, United States. *Presentation*.
- (27) **Iniguez-Rabago, A., Li, Y., Overvelde, J. T. B.**, (2019). Computational Design of Mechanically Multistable Prismatic Metamaterials. APS March Meeting. Boston, United States. *Presentation*.
- (26) **Oliveri, G., Overvelde, J. T. B.**, (2019) Inverse Design of Mechanical Metamaterials that Harness Instabilities. APS March Meeting. Boston, United States. *Presentation*.
- (25) **Oliveri, G., Overvelde, J. T. B.**, (2019) Inverse Design of Mechanical Metamaterials that Harness Instabilities. Physics@Veldhoven. Veldhoven, Netherlands. *Poster*.
- (24) **Oliveri, G., Overvelde, J. T. B.**, (2018) Inverse design of mechanical metamaterials that harness instabilities. SES. Madrid, Spain. *Presentation*.
- (23) **Iniguez-Rabago, A., Li, Y., Overvelde, J. T. B.**, (2018). Finding the Mechanically Stable States of Prismatic Architected Materials. Solvay. Brussel, Belgium. *Presentation*.
- (22) **Oliveri, G., Overvelde, J. T. B.**, (2018) Reprogramming the elastic properties of mechanical metamaterials by amplifying imperfections. Solvay. Belgium, United States. *Presentation*.
- (21) **Iniguez-Rabago, A., Li, Y., Overvelde, J. T. B.**, (2018). Finding the Mechanically Stable States in Prismatic Architected Materials. APS March Meeting. Lost Angeles, United States. *Presentation*.
- (20) **Oliveri, G., Overvelde, J. T. B.**, (2018) Reprogramming the Elastic Properties of Mechanical Metamaterials by Amplifying Imperfections. APS March Meeting. Lost Angeles, United States. *Presentation*.
- (19) **Iniguez-Rabago, A., Li, Y., Overvelde, J. T. B.**, (2017). Finding the Mechanically Stable States in Prismatic Architected Materials. Physics@Veldhoven. Veldhoven, Netherlands. *Poster*. [top three in both categories]
- (18) **Iniguez-Rabago, A., Li, Y., Overvelde, J. T. B.**, (2017). Finding the Mechanically Stable States in Prismatic Architected Materials. Soft Matter Meeting. Enschede, Netherlands. *Soundbite presentation*.
- (17) **Oliveri, G., Overvelde, J. T. B.**, (2017) Reprogramming the Elastic Properties of Mechanical Metamaterials by Amplifying Imperfections. Soft Matter Meeting. Enschede, Netherlands. *Soundbite presentation*.
- (16) **Overvelde, J. T. B.**, Weaver, J., Hoberman C., Bertoldi, K., (2017) Rational Design of Reconfigurable Architected Materials. Metamaterials Conference, Marseille, France. *Presentation*.
- (15) **Overvelde, J. T. B.**, Weaver, J., Hoberman C., Bertoldi, K., (2017). Rational Design of Reconfigurable Prismatic Architected Materials. American Physical Society Meeting. New Orleans, United States. *Presentation*.
- (14) **Overvelde, J. T. B.**, Dykstra, D. M. J., de Rooij, R., Weaver, J., Bertoldi, K., (2017). Tension Instability in a thick elastic body. American Physical Society Meeting, New Orleans, United States. *Presentation*.
- (13) **Oliveri, G., Overvelde, J. T. B.**, (2017). Reprogramming the Elastic Properties of Mechanical Metamaterials by Amplifying Imperfections. ICMS Complexity Science Winter School, Eindhoven, Netherlands. *Poster*.
- (12) **Overvelde, J. T. B.**, Dykstra, D. M. J., de Rooij, R., Weaver, J., Bertoldi, K., (2016). Tensile Instability in a Thick Elastic Body. Soft Matter Meeting, Netherlands. *Soundbite Presentation*.

- (11) **Overvelde, J. T. B.**, de Jong, T. A., Becerra, S. A., Shevchenko, Y., Whitesides, G. M., Weaver, J., Hoberman, C., Bertoldi, K., (2015). Transformable Origami-inspired Prismatic Metamaterials. Wyss retreat. Boston, United States. *Movie and Demo*.
- (10) **Overvelde, J. T. B.**, Bertoldi, K., (2015). Amplifying the Response of Soft Actuators by Harnessing Instability. New England Workshop on the Mechanics of Materials and Structures. Boston, United States. *Movie*.
- (9) **Overvelde, J. T. B.**, Kloek, T., D’haen J., Bertoldi, K., (2015). Harnessing Instability in Soft Actuators. AMOLF Designer Matter Workshop International Mechanical Engineering Conference. Amsterdam, The Netherlands. *Presentation*.
- (8) **Overvelde, J. T. B.**, de Jong, T. A., Weaver, J., Hoberman, C., Bertoldi, K., (2015). Actuated Origami-like Structures with Tunable Volume and Stiffness. APS March Meeting. San Antonio, United States. *Presentation*.
- (7) **Overvelde, J. T. B.**, Kloek, T., D’haen J., Bertoldi, K., (2014). Harnessing Instability in Soft Actuators. ASME International Mechanical Engineering Conference. Montréal, Canada. *Presentation*.
- (6) **Overvelde, J. T. B.**, Bertoldi, K., (2013). Putting Soft Sensors to the Test. New England Workshop on the Mechanics of Materials and Structures. Amherst, United States. *Movie*.
- (5) **Overvelde, J. T. B.**, Bertoldi, K., (2013). Topology Optimization of Inflatable Stretchable Structures. ASME International Mechanical Engineering Conference. San Diego, United States. *Presentation*.
- (4) **Overvelde, J. T. B.**, Shan, S., Bertoldi, K., (2012). Compaction Through Buckling in 2D Periodic, Soft and Porous Structures: Effect of Pore Shape. New England Workshop on the Mechanics of Materials and Structures. Providence, United States. *Movie*.
- (3) **Overvelde, J. T. B.**, Langelaar, M., Keulen, F. van, (2012). The Moving Node Approach in Topology Optimization - An Exploration to a Flow-inspired Meshless Method-based Topology Optimization Method. New England Workshop on the Mechanics of Materials and Structures. Providence, United States. *Poster*.
- (2) **Overvelde, J. T. B.**, Shan, S., Bertoldi, K., (2012). Non-linear Response of Soft Porous Structures: Effect of Pore Shape on their Response. Society of Engineering Science – 49th Annual Technical Meeting. Atlanta, United States. *Presentation*.
- (1) **Overvelde, J. T. B.**, Langelaar, M., Keulen, F. van (2012). Influence of the Nodal Distribution on Element-Free Galerkin Accuracy in a Topology Optimization Context. European Congress on Computational Methods in Applied Sciences and Engineering. Vienna, Austria. *Presentation*.

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## SELECTED MEDIA COVERAGE

- (41) Grob, Bart. (2018) “Het zachte robothart van Bas.” De Vrolijke Frankenstein 16 March.
- (40) Woo, Marcus. (2018) “Finding Future Tech in Ancient Art.” Nova Next 24 January. [\[web\]](#)
- (39) Overvelde, J. T. B.. (2017) “Natuurkundige Bas Overvelde gaat het bouwen: een robotboom die tot bloei komt waar je bij staat.” Trouw 11 November. [\[web\]](#)
- (38) Waterval, Dirk. (2017) “Programmeerbare Metamaterialen” Quantum Universe 19 September. [\[web\]](#)
- (37) Van Calmthout, Martijn. (2017) “Aan tafel met Frankenstein - De gemaakte natuur.” Talk show Museum Boerhaave - Nacht van Kunst en Kennis 16 September.
- (36) Visscher, Marc-Robin. (2017) “Zacht robotisch kunsthart in de maak.” Radio show NPO1 Nieuws en Co 4 August. [\[web\]](#)
- (35) Iking, Harm. (2017) “Toekomstmaterialen.” Hypothese 12 May. [\[pdf\]](#)
- (34) Van Calmthout, Martijn. (2017) “Hogere knutselkunde.” De Volkskrant 11 March. [\[web\]](#)[\[web\]](#)
- (33) Beekhuis, Mark. (2016) “Een origami-materiaal dat geluid verandert.” Radio show BNR Wetenschap vandaag 28 November. [\[web\]](#)
- (32) Karhof, Joost. (2016) “Wetenschappers adopteren Origami.” Radio show NPO1 Nieuws en Co 4 November. [\[web\]](#)
- (31) Vives, Francois-Xavier. (2016) “The Origami Code.” Documentary at Inscience Festival 2-6 November. [\[web\]](#)
- (30) Aan de Brugh, Marcel. (2016) “Octopus als Robot.” NRC Handelsblad and NRC Next 3 September. [\[pdf\]](#) [\[pdf\]](#)

- (29) Van Kasteren, Joost. (2016) “Dichte muur krijgt gaten met een keertje vouwen.” NRC Handelsblad 16 April. [\[pdf\]](#)
- (28) Cookson, Clive. (2016) “Origami comes into the tech fold.” Financial Times 26 March. [\[pdf\]](#)
- (27) Hansman, Heather. (2016) “A New Material Could Make Medical Devices That Expand and Collapse.” Smithsonian 18 March. [\[web\]](#)
- (26) Joosten, Carla. (2016) “Zachte Robotica.” Elsevier 17 March. [\[pdf\]](#)
- (25) Knapton, Sarah. (2016) “Bizarre shape-shifting material invented by Harvard.” The Telegraph 11 March. [\[web\]](#)
- (24) Web editor (2016) “Researchers design versatile shapeshifting material.” ResearchGate 11 March. [\[web\]](#)
- (23) Ceurstemont, Sandrine. (2016) “Shape-shifting matter could let houses crumple themselves away.” New Scientist 11 March. [\[web\]](#)
- (22) Reader, Ruth. (2016) “Researchers Have Created a Shapeshifting Material Inspired by Origami.” Mic 11 March. [\[web\]](#)
- (21) Web editor (2016) “Harvard team develops origami-inspired 3D structural material.” The Engineer 11 March. [\[web\]](#)
- (20) Wassink, Jos. (2016) “Transforming materials.” DELTA 11 March. [\[web\]](#)
- (19) Burrows, Leah. (2016) “Transforming materials.” Harvard News and Views 11 March. [\[web\]](#)
- (18) Web editor (2015) “Delft Students Help Make More Dextrous Robots.” TU Delft Robotics Institute 27 August. [\[web\]](#) and other TU Delft web publications [\[EWI\]](#)[\[LR\]](#)[\[3ME\]](#)
- (17) Edelman, Peter. (2015) “Niet-lineair gedrag handig gebruikt in kunstmatige spier.” Mechatronica & Machinebouw 21 August. [\[web\]](#)
- (16) Wassink, Jos. (2015) “Ballooning muscles for robots.” DELTA 20 August. [\[web\]](#)
- (15) Web editor (2015) “Soft actuator could remove need for robotic tethers.” The Engineer 18 August. [\[web\]](#)
- (14) Burrows, Leah. (2015) “Controlling the uncontrollable.” Harvard News and Views 17 August. [\[web\]](#)
- (13) Wright, Katherine. (2015) “Runaway buckling.” APS Physics 21 July. [\[web\]](#)
- (12) Zegers, Gabby. (2015) “Metamaterial undermines 250-year-old construction principles.” FOM 21 July. [\[web\]](#)
- (11) Morad, Renee. (2015) “Jumping, Froglike Robot Takes a Big Leap Forward.” Robotics, Discovery 9 July. [\[web\]](#)
- (10) Ackerman, Evan. (2015) “3D-Printed Explosive Jumping Robot Combines Firm and Squishy Parts.” IEEE Spectrum, 9 July. [\[web\]](#)
- (9) Burrows, Leah. (2015) “Harvard Researchers Create Jumping Soft Robot Using 3-D Printer.” Harvard Gazette 9 July. [\[web\]](#)
- (8) Feltman, Rachel. (2015) “This Jumping, Squishy Robot Looks Like a Tiny UFO.” Speaking of Science, The Washington Post 9 July. [\[web\]](#)
- (7) Herkewitz, William. (2015) “Nearly Unbreakable Soft Robot Ignites Explosions to Jump.” New Technology, Popular Mechanics 9 July. [\[web\]](#)
- (6) Ball, Philip. (2014) “Soft-hearted Robots.” News and Views, Nature Materials Vol. 13 April. [\[pdf\]](#)
- (5) Martiradonna, Luigi. (2014) “Heart Twists.” Research Highlight, Nature Materials Vol. 13 January. [\[pdf\]](#)
- (4) Aan de Brugh, Marcel. (2014) “Een nieuwe hartkamer van zachte kunststof.” NRC Handelsblad 28 February. [\[pdf\]](#)
- (3) Kusek, Kristen. (2014), “Artificial muscles do the twist.” Wyss Institute 26 February. [\[web\]](#)
- (2) Bosman, Annemieke. (2013) “Vliegende Hollander.” Transfer Magazine, 4. [\[pdf\]](#)
- (1) Elshof, Loes. (2009) “Excellence Program.” TU Delft. [\[video\]](#)

## DOCUMENTARIES AND EXHIBITIONS

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- (7) “?Bouw een wiskundige figuur” (Feb 2019), workshop and exhibit at NEMO, Amsterdam NL. (NL).
- (6) “RainMaker” (Sep 2018), exhibition at FabLearn and Maker Faire (*Winner of the Maker of Merit Award*), Eindhoven (NL).

- (5) “Frankie - The artificial starfish” (Mar 2018 - Oct 2018), exhibition at Rijksmuseum Boerhaave, Leiden (NL)
- (4) “Edge of Chaos” (Dec 2017 - Jan 2019), exhibition on world tour at (WoeLab in Lomé (TG); La Gaité Lyrique in Paris (FR); Cinekid in Amsterdam (NL); KIKK Festival in Namur (BE).
- (3) “Morphing Crystals” ((Dec 2017 - Apr 2019), exhibition at Rijksmuseum Boerhaave, Leiden (NL)
- (2) “10 Degreeesh” (Sept 2016 - Jan 2017), exhibition at Le Laboratoire, Cambridge (US)
- (1) “The Origami Code” (2016), documentary by Francois-Xavier Vives, Dutch premiere INScience, aired NPO on 6 Nov. (min 32:49 - 35:01)

## JOURNAL PUBLICATIONS

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- (21) Oliveri, G., Overvelde, J.T.B., Inverse design of mechanical metamaterials that harness instabilities. *In preparation*.
- (20) McClintock, H.D., Doshi, N.D., Iniguez-Rabago, A., Jayaram, K., Overvelde, J.T.B., Jafferis, N.T., Weaver, J.C., Wood, R.J., A sarrus linkage-based millimeter-scale metamaterial. *In preparation*.
- (19) Iniguez-Rabago, A., Li, Y., Overvelde, J.T.B., (2018). Exploring Multistability in Prismatic Metamaterials through Local Actuation. *Submitted*.
- (18) Mogas-Soldevila, L., Duro-Royo, J., Lizardo, D., Weaver, J., Overvelde, J.T.B., DiMaski, E., Bertoldi, K., Oxman, N., (2018). Fabrication-informed Multi-functional Anisotropy across Length Scales. *Submitted*.
- (17) Vasios, N., Gross, A. J., Soifer, S., Overvelde, J. T. B.,\* Bertoldi, K.,\* (2019). Harnessing Viscous Flow to Simplify the Actuation of Fluidic Soft Robots. *Soft Robotics*. [[Harvard News](#)] [[web](#)] [[pdf](#)]
- (16) Mulla, Y., **Oliveri, G., Overvelde, J. T. B.**, Koenderink, G. H., (2018). Crack Initiation in Viscoelastic Materials. *PRL*, 120, 268002. [[web](#)] [[pdf](#)]
- (15) **Overvelde, J. T. B.**, Weaver, J., Hoberman, C., Bertoldi, K., (2017). Rational Design of Reconfigurable Prismatic Architected Materials. *Nature*, 541, 347-352. [[De Volkskrant](#)] [[De Volkskrant online](#)] [[News & Views in Nature](#)] [[Harvard News](#)] [[web](#)] [[pdf](#)]
- (14) Wang, Z., Galloway, K., **Overvelde, J. T. B.**, Polygerinos, P., Bertoldi, K., Walsh, C. J., (2016). Interaction Forces of Soft Fiber Reinforced Bending Actuators. *IEEE/ASME Transactions on Mechatronics*, 99. [[web](#)] [[pdf](#)]
- (13) Babaei, S., **Overvelde, J. T. B.**, Chen, E. R., Tournat, V., Bertoldi, K., (2016). Reconfigurable Origami-inspired Acoustic Waveguides. *Science Advances*, 2(11), e1601019. [[web](#)] [[pdf](#)]
- (12) **Overvelde, J. T. B.**, Dykstra, D. M. J., de Rooij, R., Weaver, J., Bertoldi, K., (2016). Tensile Instability in a Thick Elastic Body. *Physical Review Letters*. [[Harvard News](#)] [[web](#)] [[pdf](#)]
- (11) **Overvelde, J. T. B.**, de Jong, T. A., Becerra S. A., Shevchenko, Y., Whitesides, G. M., Weaver, J., Hoberman, C., Bertoldi, K., (2016). Actuated Three-dimensional Origami-like Metamaterial with Tunable Volume and Stiffness. *Nature Communications*. [[NRC Handelsblad](#)] [[Financial Times](#)] [[Tech Insider](#)] [[Daily Mail](#)] [[The Telegraph](#)] [[Smithsonian](#)] [[ResearchGate featured article](#)] [[New Scientist](#)] [[Mic](#)] [[The Engineer](#)] [[TU Delta](#)] [[Harvard News](#)] [[web](#)] [[pdf](#)]
- (10) Pouya, C., **Overvelde, J. T. B.**, Kolle, M., Aizenberg, J., Bertoldi, K., Weaver, J. C., Vukusic, P., (2015). Characterisation of a Mechanically Tuneable Gyroid Photonic Crystal Inspired by the Butterfly *Parides sesostris*. *Advanced Optical Materials*. [[web](#)] [[pdf](#)]
- (9) **Overvelde, J. T. B.**, Kloek, T., D’haen J. J. A., Bertoldi, K., (2015). Amplifying the Response of Soft Actuators by Harnessing Instability. *Proceedings of the National Academy of Sciences*. [[The Engineer](#)][[TU Delta](#)][[Harvard News](#)] [[web](#)] [[cover](#)][[pdf](#)]
- (8) Coulais, C., **Overvelde, J. T. B.**, Lubbers, L. A., Bertoldi, K., van Hecke, M., (2015). Discontinuous Buckling of Wide Beams and Metabeams. *Physical Review Letters*. [[FOM News](#)] [[web](#)] [[pdf](#)]
- (7) Bartlett, N. W., Tolley, M. T., **Overvelde, J. T. B.**, Weaver, J., Mosadegh, B., Bertoldi, K., Whitesides, G. M., Wood, R. J., (2015). A 3D Printed, Functionally Graded Soft Robot Powered by Combustion. *Science* [[The Washington Post](#)][[Discovery](#)][[Harvard News](#)][[Popular Mechanics](#)] [[web](#)] [[pdf](#)]
- (6) Polygerinos, P., Galloway, K., **Overvelde, J. T. B.**, Wang, Z., Wood, R., Bertoldi, K., Walsh, C. J., (2014). Modeling of Soft Fiber-reinforced Bending Actuators. *IEEE Transactions on Robotics* [[web](#)] [[pdf](#)]

- (5) **Overvelde, J. T. B.**, Mengüç, Y., Polygerinos, P., Wang, Y., Wang, Z., Walsh, C. J., Wood, R. J., Bertoldi, K., (2014). Numerical Mechanical and Electrical Analysis of Soft Liquid-embedded Deformation Sensors. *Extreme Mechanics Letters*. [[web](#)] [[pdf](#)]
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